LESSON PLAN FOR SUMMER SESSION (2023-24)

ROGRAM	ME : CIV	IL ENGI	NEERING	NAME OF THE FACULTY: MR. SUBRAT KUMAR PANIGRAHI			
DURSE N	NAME : LA	ND SUR	VEY PRACTICE -II	SESSION: 2023-24			
MESTE	CODE ; PR	.2		DATE: 16.01.2024 To 26.04.2024			
	WEEK: 5						
	ERIODS:75	,					
WEEK	PERIODS	UNITS		TOPICS			
	15.00	1.0 TRIGONOMETRICAL SURVEYING & TACHEOMETRY:					
SALES OF THE SALES	1	BATE III		objects whose bases are accessible			
1-4	2			objects whose bases are accessible			
lst	3						
	4	10 10	1.2 Determination of stadia const	objects whose bases are accessible			
	5		1.2 Determination of stadia const				
	6	1	1.2 Determination of stadia const				
	7	int.		listance an elevation with Staff vertical, by stadia method			
2nd	8			listance an elevation with Staff vertical, by stadia method			
	9			distance an elevation with Staff vertical, by stadia method			
Pho D	10			distance an elevation with Staff vertical, by stadia method			
	11		2.1 Setting out a simple circular	curve by offsets from long chord			
2.1	12		2.1 Setting out a simple circular				
3rd	13		2.2 Setting out a simple circular	curve by offsets from the tangent			
	15	1	2.2 Setting out a simple circular	curve by offsets from the tangent curve by offsets from chords produces			
FIRM	16	2		curve by offsets from chords produces curve by Rankine's method of tangent angle (Deflection angles)			
	17	Talk	g can a sample en eului	, and a second angle (Second angles)			
4th	18	1	2.5 Setting out the foundation lin	ne for a culvert			
	19	1000	2 CD: '11'				
			2.6 Dividing an area into plots o	I given size			
	21		3.1 Physical Map				
- 1	22		3.2 Topographic Map				
5th	23	30 30	3.3 Road Map				
	24	10 176	3.4 Political Map				
10000	25	3	3.5 Economic & Resources Map				
	26	100	3.6 Thematic Map				
6th	28	11349	3.7 Climate Map 3.8 Open Series map and Defense	Series Man			
	29		3.8 Open Series map and Defense				
	30		3.8 Open Series map and Defense				
	31			Signals, Errors of GPS, Positioning Methods			
7th	32	1	4.1 GPS: - Global Positioning, GPS 4.2 DGPS: - Differential Global Pos	Signals, Errors of GPS, Positioning Methods			
/th	34	1000	4.2 DGPS: - Differential Global Po				
400	35	180	4.2.1 Base Station Setup				
1350	36		4.2.1 Base Station Setup				
17.33	37		4.2.2 Rover GPS Set up				
8th	38		4.2.2 Rover GPS Set up	10001			
1727	39	4	4.2.3 Download, Post-Process a				
1000	40	- 1750	4.2.3 Download, Post-Process				
100	41	100	4.2.4 Sequence to download G				
	42	-	4.2.4 Sequence to download G.				
9th	43	4	4.2.5 Sequence to Post-Process				
	44		4.2.5 Sequence to Post-Process				
	45	12 1	4.2.6 Sequence to export post p				
1 1 1 1	46		4.2.6 Sequence to export post	process GPS data			
ALTER V	47	1 Bridge	4.2.7 Sequence to export GPS				
10th	48	Also III	4.2.7 Sequence to export GPS 4.3 ETS: - Electronic Total Sta	Time tage of the			
100	49	- 100	4.3.1 Distance Measurement	MION.			
THE REAL PROPERTY.	THE REAL PROPERTY.						
	50	100	4.3.2 Angle Measurement				
	51		4.3.3 Leveling				
110	h 52	100	4.3.4 Determining position 4.3.5 Reference networks				
In	54		4.3.6 Errors and Accuracy	THE RESIDENCE OF THE PARTY OF T			
	55		4 3 6 Errors and Accuracy				
	56		5.1 Components of GIS, Integ	ration of Spatial and Attribute Information			
E 123 14	57	THE STATE OF	5.1 Components of GIS, Integ	ration of Sand Land Attribute Information			

12th	58		5.2 Three Views of Information System
	59		5.2 Three Views of Information System
	60		5.3 Spatial Data Model
	61		5.3 Spatial Data Model
	62		5.4 Attribute Data Management and Metadata Concept
13th	63		5.4 Attribute Data Management and Metadata Concept
100000	64		5.5 Prepare data and adding to Arc Map.
	65		5.5 Prepare data and adding to Are Map.
	66	5	5.6 Organizing data as layers.
1 3 3 6 6	67		5.6 Organizing data as layers.
14th	68		5.7 Editing the layers.
12000	69		5.8 Switching to Layout View.
	70		5.9 Change page orientation.
	71		5.10 Removing Borders.
	72		5.10 Removing Borders.
15th	73		5.11 Adding and editing map information.
1	74		5.11 Adding and editing map information.
	75		5.12 Finalize the map
Concern f	aculty 124)	HOD Acade vic Coordinator. Principal GP Nabarangpur Representation of the principal GP Nabarangpur